

The maximum k -colorable subgraph problem and orbitopes

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ABSTRACT

Given an undirected node-weighted graph and a positive integer k , the maximum k -colorable subgraph problem is to select a k -colorable induced subgraph of largest weight. The natural integer programming formulation for this problem exhibits a high degree of symmetry which arises by permuting the color classes. It is well known that such symmetry has negative effects on the performance of branch-and-cut algorithms. Orbitopes are a polyhedral way to handle such symmetry and were introduced in Kaibel and Pfetsch (2008) [2].

The main goal of this paper is to investigate the polyhedral consequences of combining problem-specific structure with orbitope structure. We first show that the LP-bound of the integer programming formulation mentioned above can only be slightly improved by adding a complete orbitope description. We therefore investigate several classes of facet-defining inequalities for the polytope obtained by taking the convex hull of feasible solutions for the maximum k -colorable subgraph problem that are contained in the orbitope. We study conditions under which facet-defining inequalities for the polytope associated with the maximum k -colorable subgraph problem and the orbitope remain facet-defining for the combined polytope or can be modified to yield facets. It turns out that the results depend on both the structure and the labeling of the underlying graph.

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1. Introduction

Symmetry in integer programs (IPs) has been recognized to harm the performance of branch-and-cut algorithms for a long time. One reason for the deteriorating effect of symmetries is that symmetric solutions appear repeatedly in the search tree, without giving new information about the optimal solution. In recent years, several successful methods to handle such symmetry have been developed. Margot [1] provides an excellent overview.

One line of research on symmetry handling aims at techniques to avoid visiting symmetric subproblems during search. However, the presence of symmetry may also be responsible for weak bounds of the linear programming (LP) relaxation: the barycenter of the solutions in an orbit with respect to the symmetry lies within the convex hull of all feasible solutions. Depending on the problem, this (fractional) point frequently has an objective that is far away from the optimal solution value of the IP. This leads to weak LP-bounds.

One way to deal with such weak LP-bounds is to handle symmetry via polyhedral methods. For a particular symmetry which, however, often appears in IP-models used in practice, this can be done via so-called orbitopes, introduced in [2]. Here, the IP-model contains an assignment structure in which objects should be assigned to symmetric object classes, i.e., there are binary variables x_{ij} that indicate whether object i should be assigned to class j . The symmetry arises from the fact that the classes are indistinguishable, i.e., we can arbitrarily permute the classes without changing the structure of the solution

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(the objective function value has to be invariant under this operation). In other words, the full symmetric group acts on the columns of the matrix x . So-called packing orbitopes are the convex hull of those matrices that are lexicographically maximal within each orbit subject to the condition that each row of x contains at most one 1. Complete linear descriptions of these orbitopes can be given, see Section 3.1 for more precise definitions and results.

In this paper, we study the maximum k -colorable subgraph problem, which provides a particular application for the above methodology. Here, given an undirected (node-weighted) graph and a positive integer k , the problem is to find a maximum induced subgraph that is k -colorable, i.e., we can assign colors to each node in the subgraph such that adjacent nodes receive different colors. Thus, the nodes correspond to the objects that have to be assigned to color classes, subject to the condition that each node is assigned to at most one class. This problem is interesting for its own sake. It has rarely been studied in the literature, supposedly because it is closely connected to both the more prominent graph coloring problem and the stable set problem.

The goal of this paper is to investigate the effect of symmetry handling on the linear programming bound and more generally on the polyhedral structure of the corresponding polytope. We show that the LP-bounds of a straight-forward IP-formulation of the maximum k -colorable subgraph problem only slightly improve when we add (complete) symmetry handling inequalities (Section 3.2). Thus, to make progress on the LP-bounds one has to include problem-specific structure, either by adding valid inequalities for the polytope corresponding to the original problem without symmetry handling or by considering the polytope in which symmetry has been handled by orbitopes. We briefly discuss the first possibility in Section 2. We then concentrate on the second possibility. Our main focus lies on giving conditions under which inequalities in the original IP-formulation of the maximum k -colorable subgraph problem and of orbitopes remain facets for the polytope obtained by taking the convex hull of feasible solutions for the maximum k -colorable subgraph problem that are contained in the orbitope. Whenever these inequalities do not define facets, we study how they can be strengthened to obtain facet-defining inequalities using problem-specific structure. We investigate each inequality in the defining IP-formulation. It turns out that the conditions for which the original or strengthened inequalities define facets can be quite technical. They clearly show, however, that the structure of the underlying graph of the maximum k -colorable subgraph problem is crucial for these results. Moreover, the results depend on the labeling of the nodes of the graph, i.e., they depend on the order of the rows of the matrix of assignment variables. Thus, the results of this paper can be used to distinguish different orderings of the nodes.

One general remark is that the methods studied in this paper do not take symmetries of the graph into account. Graph symmetry handling is discussed in [3], which also contains preliminary computational results evaluating the performance of a branch-and-cut approach.

A brief outline of this paper is as follows. We discuss related work in Section 1.1. In Section 1.2, we introduce the maximum k -colorable subgraph problem and state results on its computational complexity. In Section 2, we discuss several (facet-defining) inequalities that are valid for the polytope corresponding to the case in which symmetry has not been taken into account. In Section 3, we review orbitopes and show in Section 3.2 that the LP-bounds only slightly improve by adding orbitope symmetry handling inequalities. In Section 4, we study the polyhedral consequences of combining orbitope symmetry handling inequalities with problem-specific inequalities of the maximum k -colorable subgraph problem. We then deal with the different inequalities in turn. In Section 4.1, we consider packing inequalities, in Section 4.2, we study shifted column inequalities, and finally, in Section 4.3, we investigate clique shifted column inequalities.

This paper is partially based on the diploma thesis [4].

1.1. Related work

As mentioned above, several approaches dealing with symmetries in integer programming have appeared in the literature. Most notably, in a series of papers, Margot [5–7] developed a methodology to (completely) handle symmetry within the branch-and-bound tree. Linderöth et al. [8,9] investigate a variant based on branching on constraints, which allows to recompute symmetries for the subproblems in the tree. Orbitopes were introduced in [2]. Faenza and Kaibel [10] give a nice proof of the completeness of the linear description. Efficient fixing of variables using orbitope symmetry was developed in [11]; this paper also presents computational results for a graph partitioning problem. Friedman [12] discusses symmetry handling via so-called fundamental domains. We refer to Margot [1] for an overview of all these approaches. The handling of symmetries has also been extensively discussed in the constraint programming literature. Gent et al. [13] as well as Lecoutre and Tabary [14] provide overviews.

A further approach is to avoid symmetries by reformulation. For instance, Mehrotra and Trick [15] present a formulation of the graph coloring problem that avoids color symmetries. This can be adapted to the maximum k -colorable subgraph problem, but this formulation complicates the expression of the weighted maximum k -colorable subgraph problem. Another example for reformulation that avoids symmetries was presented by Valério de Carvalho [16] for the bin-packing problem.

The combination of orbitope and problem-specific structure was studied by Faenza [17] with respect to the graph coloring problem. Since the corresponding polytope is not full-dimensional, unfortunately the results and proofs become quite complicated. Our study on the maximum k -colorable subgraph problem avoids some of these obstacles. As mentioned above it is based on the thesis [4].

Polyhedral properties of the maximum k -colorable subgraph problem have been rarely treated so far. For $k = 2$, several polyhedral results exist. For example, Fouilhoux and Mahjoub [18] identify several facets and provide separation algorithms.

As far as we know, the corresponding polytopes for arbitrary k have not been investigated. However, several applications of the maximum k -colorable subgraph problem appear in the literature. We list some of these here.

The *wave length assignment problem* arises in the design of optical networks (e.g., fiber glass telecommunication networks). Here, wave lengths have to be assigned to as many pre-routed light paths as possible such that intersecting light paths do not use the same wave length, see [19]. A light path consists of links and fibers and intersect at links only. The number of wave lengths is restricted by the capacity of the fibers. Under the assumption that the capacity of each link is 1 and that each light path can receive at most one wavelength, this leads to a special case of the maximum k -colorable subgraph: wavelengths correspond to colors and light paths to nodes. Nodes are adjacent if the light paths share a link.

In the literature, the driving applications of the maximum k -colorable subgraph and especially the maximum bipartite induced subgraph problem have been so-called *via minimization problems*, see [18,20]. Via minimization problems arise in the design of integrated circuits. Other applications include *register allocation* and *job scheduling*, see [21].

1.2. Notation, basic definitions and complexity

We use the following notation throughout the article.

For an integer $n \geq 1$, let $[n] := \{1, 2, \dots, n\}$. For $x \in \mathbb{R}^{[n] \times [k]}$ and $S \subseteq [n] \times [k]$, we write $x(S) := \sum_{i,j \in S} x_{ij}$. We use row_i for the set $\{(i, 1), (i, 2), \dots, (i, k)\}$ and col_i for the set $\{(1, i), (2, i), \dots, (n, i)\}$. By $\mathbf{0}$ we denote a zero matrix of appropriate dimensions.

Let $G = (V, E)$ be an undirected graph consisting of a set of nodes V with cardinality $n := |V|$ and a set of edges $E \subseteq \binom{V}{2}$. We will often need an order of the nodes in V and thus assume that $V := \{1, \dots, n\}$; in particular, we can directly compare nodes, e.g., $u < v$ for $u, v \in V$. Moreover, let $w : V \rightarrow \mathbb{R}$ be a weight function. We denote by $G[V']$ the subgraph induced by $V' \subseteq V$. Thus, the set of edges of $G[V']$ is $\left\{e \in E : e \in \binom{V'}{2}\right\}$.

For a positive integer k , G is said to be *k -colorable* if we can assign to each node in G a color (number) in $[k]$ such that adjacent nodes do not have the same color.

Definition 1. For a positive integer k and the graph G with weights w , the (*weighted*) *maximum k -colorable subgraph problem* consists of finding a set $V' \subseteq V$ that induces a k -colorable subgraph and has maximum weight $\sum_{v \in V'} w(v)$. If $w(v) = 1$ for all $v \in V$, we obtain the *unweighted maximum k -colorable subgraph problem*.

In this problem, any node that has a negative weight will not appear in an optimal solution. Thus, we will assume that w is non-negative in the following. Moreover, we will assume without loss of generality that G is simple, because nodes contained in loops will never be part of an optimal solution, and parallel edges can be replaced by a single edge without changing the problem. Finally, we assume that $1 \leq k < n$, since otherwise the problem becomes trivial.

The above problem is related to the graph coloring problem, where the goal is to find the smallest k such that G is k -colorable. Obviously, by using binary search, one can reduce the coloring problem to the unweighted maximum k -colorable subgraph problem. Thus, the latter is (strongly) \mathcal{NP} -hard, if k is part of the input.

The maximum k -colorable subgraph problem is also related to the stable set problem in two ways: first, each set of nodes receiving the same color has to be a *stable set*, i.e., there are no edges between any two nodes in this set. The second relation can be derived as follows.

For a node v , the *neighborhood* $\Gamma(v)$ of node v contains all nodes adjacent to v , i.e.,

$$\Gamma(v) := \{u \in V : \{u, v\} \in E\}.$$

The *closed neighborhood* of v is $\overline{\Gamma}(v) := \Gamma(v) \cup \{v\}$. The *degree* of node v is defined as $\delta(v) := |\Gamma(v)|$. A *clique* in a graph is a set of nodes $C \neq \emptyset$ such that for all $u, v \in C$, $u \neq v$, we have $\{u, v\} \in E$; a clique is *maximal*, if there is no other clique containing it. The *complete graph* on n nodes is a graph whose entire set of nodes $[n]$ forms a clique, and we denote it by K_n .

Definition 2 (*Cartesian Graph Product*). Let $G = (V, E)$ and $G' = (V', E')$ be two graphs. The (*Cartesian*) *product graph* $G \times G'$ of G and G' has the Cartesian product $V \times V'$ as its node set. For $u, v \in V$ and $u', v' \in V'$, $\{(u, u'), (v, v')\}$ is an edge in $G \times G'$ if and only if

- $u = v$ and $\{u', v'\} \in E'$, or
- $u' = v'$ and $\{u, v\} \in E$.

It is easy to see that the weighted maximum k -colorable subgraph problem for G can be reduced to the weighted maximum stable set problem on the product graph $G \times K_k$, where the weights W of $G \times K_k$ are defined as $W(v, j) = w(v)$ for all $v \in V, j \in [k]$; this was observed first by Narasimhan [20].

The following result gives an extension of a result by Fouilhoux and Mahjoub [18] for $k = 2$ and deals with the reverse reduction.

Lemma 1. Let $k \in \mathbb{Z}$, $1 \leq k < n$, be fixed. The maximum stable set problem can be reduced to the maximum k -colorable subgraph problem in polynomial time in n .

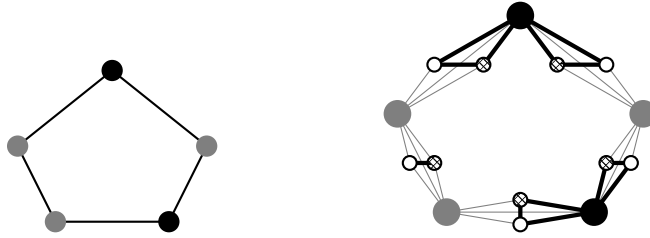


Fig. 1. Illustration of the proof of Lemma 1 for $k = 3$. Left: a maximum stable set in the 5-cycle depicted with black nodes. Right: the resulting graph with a maximum (black, white, crossed)-colorable subgraph (for every edge we have added a K_2); nodes and edges in gray do not belong to the selected 3-colored subgraph.

Proof. Finding a stable set of maximum weight in a graph $G' = (V', E')$ can be reduced to finding a maximum k -colorable subgraph in a graph $G = (V, E)$ that is obtained from G' as follows. The graph G has all edges and nodes of G' . Additionally, for every edge $\{u, v\} \in E'$, we add a complete graph K_{k-1} , such that all nodes in K_{k-1} are adjacent to both u and v . Fig. 1 shows an example of the construction.

We assign a sufficiently large positive weight to the nodes of the complete graphs such that they must be chosen in any optimal solution of the maximum k -colorable subgraph problem. Thus, each node $v \in V'$ has at least $k - 1$ neighbors colored with different colors in an optimal k -colorable subgraph of G . Hence, for $\{u, v\} \in E'$ nodes u and v cannot both be contained in an optimal subgraph for G . It follows that the nodes u, v are contained in a maximum k -colorable subgraph if and only if u, v are part of a maximum stable set.

The reduction is clearly polynomial in the size of G , w , and in k . \square

It follows from Lemma 1 that the maximum k -colorable subgraph problem is (strongly) \mathcal{NP} -hard for any fixed k with $1 \leq k < n$. Note, however, that the reduction uses several different weights.

A stronger result follows from the work of Lewis and Yannakakis [22], who showed that the maximum subgraph problem for hereditary properties (fulfilling certain requirements) is \mathcal{NP} -hard. If we define the hereditary property as “the graph is k -colorable”, we obtain the (unweighted) maximum k -colorable subgraph problem. Hence, the *unweighted* maximum k -colorable subgraph problem is \mathcal{NP} -hard for any fixed k , $1 \leq k < n$.

Moreover, Lund and Yannakakis [23] showed that such maximum subgraph problems for hereditary properties cannot be approximated within n^ε for some $\varepsilon > 0$ (depending on the property) unless $\mathcal{NP} = \mathcal{P}$; see [23] for stronger results under more restrictive assumptions. Thus, the (unweighted) maximum k -colorable subgraph problem is hard to approximate for any fixed k , $1 \leq k < n$; note that Lemma 1 does not provide an approximation preserving reduction. For $k = 1$, it is as hard to approximate as the maximum stable set problem.

We briefly sum up results on the complexity of the maximum k -colorable subgraph for $k \in \{2, 3\}$. For $k = 2$, the maximum k -colorable subgraph problem is \mathcal{NP} -hard even in graphs with maximum degree three and in planar graphs with maximum degree greater than four, see [24]. For $k = 3$, the maximum k -colorable subgraph problem is \mathcal{NP} -hard in planar graphs, because we can reduce the problem of deciding whether a planar graph is 3-colorable to the maximum k -colorable subgraph problem.

2. The k -colored subgraph polytope

In this section, we will briefly collect results on the polytope corresponding to the maximum k -colorable subgraph problem (without symmetry handling). After reviewing orbitope symmetry handling in the next section, we will then investigate the combination with symmetry handling in Section 4.

We consider the following IP-formulation for the maximum k -colorable subgraph problem:

$$(\text{IP}_k(G)) \quad \max \sum_{v \in V} w(v) \sum_{j \in [k]} x_{vj} \quad (1)$$

$$x_{uj} + x_{vj} \leq 1 \quad \forall \{u, v\} \in E, j \in [k] \quad (2)$$

$$x(\text{row}_v) \leq 1 \quad \forall v \in V \quad (3)$$

$$x_{vj} \in \{0, 1\} \quad \forall v \in V, j \in [k]. \quad (4)$$

Let x be a solution of (2)–(4). Because of the *packing inequalities* (3), $\sum_{j \in [k]} x_{vj}$ is 1 if and only if node v is in the selected subgraph (i.e., colored). The *edge inequalities* (2) guarantee that adjacent nodes do not have the same color in a colored subgraph. Thus, the objective function represents the weight of the selected subgraph.

The k -colored subgraph polytope corresponding to the maximum k -colorable subgraph problem is

$$P_k(G) := \text{conv}\{x \in \{0, 1\}^{V \times [k]} : x \text{ satisfies (2) and (3)}\}.$$

For $u \in V$ and $j \in [k]$, let E^{uj} be the (u, j) -unit matrix, i.e., E^{uj} has a 1 at position (u, j) and is 0 otherwise. Since E^{uj} , for all $u \in V$ and $j \in [k]$, and the zero matrix are all contained in $P_k(G)$ (since G is simple), we have $\dim(P_k(G)) = n \cdot k$, i.e., the polytope is full-dimensional. For $k = 1$, $P_k(G)$ is (isomorphic to) the *stable set polytope*, which we denote by $P(G)$.

2.1. Valid inequalities

In this section we mention some valid/facet-defining inequalities for $P_k(G)$.

First, easy inspection shows that the *non-negativity inequalities* $x_{vj} \geq 0$ define facets of $P_k(G)$ for all $v \in V, j \in [k]$. If $k > 1$, each inequality $x_{vj} \leq 1, v \in V, j \in [k]$, is dominated by the packing inequality $x(\text{row}_i) \leq 1$. Moreover, the packing inequalities (3) define facets of $P_k(G)$, see [4].

Remark 2. The polytope $P_k(G)$ is down-monotone, i.e., if $x \leq y \in P_k(G)$, then also $x \in P_k(G)$. Hammer et al. [25] showed for such polytopes that every facet-defining inequality $\alpha^T x \leq \beta$ has $\beta \geq 0$. If $\beta = 0$, it is a non-negativity inequality, which always defines a facet. If $\beta > 0$ then $\alpha_{vj} \geq 0$ for all $v \in V, j \in [k]$.

We obtain the following result by applying general projection theory, see, for instance, Theorem 16 in [26].

Lemma 3. Let $j \in [k]$ and let

$$\sum_{v \in V} \alpha_v x_{vj} \leq \beta$$

define a facet of $P_k(G)$. Then $\alpha^T y \leq \beta$ defines a facet of $P(G)$.

Thus, the projection of facets whose support is restricted to a column are facets of the stable set polytope. Conversely, we can “trivially lift” facet-defining inequalities for $P(G)$ to facet-defining inequalities of $P_k(G)$.

Proposition 4. Assume that

$$\alpha^T y \leq \beta \tag{5}$$

defines a non-trivial facet of $P(G)$. Then, the inequality

$$\sum_{v \in V} \alpha_v x_{vj} \leq \beta, \tag{6}$$

defines a facet of $P_k(G)$ for all $j \in [k]$.

Proof. Since (5) defines a non-trivial facet, we have $\alpha \geq 0$ and $\beta > 0$, using the results of Hammer et al. [25] for $P(G)$ (see also Remark 2). Moreover, there exists a set $\mathcal{A} \subseteq P(G)$, $|\mathcal{A}| = n$, of affinely independent, non-zero points that fulfill inequality (5) with equality.

Let $j \in [k]$ be fixed. For each point $\tilde{x} \in P(G)$, we define a matrix $\tilde{X} \in P_k(G)$ whose j th column equals \tilde{x} and is 0 otherwise. Then for each $\tilde{x} \in \mathcal{A}$, \tilde{X} fulfills (6) with equality. To find additional $n(k-1)$ affinely independent matrices that fulfill (6) with equality, we proceed as follows.

For each $i \in [n]$, there exists a point $\tilde{x} \in \mathcal{A}$ with $\tilde{x}_i = 0$; otherwise, every point in the facet defined by (5) would satisfy $\tilde{x}_i = 1$, i.e., would be contained in the face defined by $x_i \leq 1$, a contradiction, since (5) defines a non-trivial facet. Thus, for $t \neq j$, the matrix $E^{it} + \tilde{X}$ does not violate any packing inequality and is contained in $P_k(G)$ (recall that E^{it} is the (i, t) -unit matrix). Moreover, it fulfills (6) with equality.

In total, we have $n \cdot k$ many matrices that fulfill (6) with equality. It is easy to see that these matrices are affinely independent. Thus, (6) defines a facet of $P_k(G)$. \square

Hence, several well known inequality classes for $P(G)$ are also valid for $P_k(G)$, e.g., *odd hole*, *odd antihole*, and *odd wheel inequalities*, see [27]. We will often use *clique inequalities* $\sum_{v \in C} x_{vj} \leq 1$, for $j \in [k]$, in the following. It is well known that clique inequalities $\sum_{v \in C} y_v \leq 1$ define facets of $P(G)$ if and only if the clique C is maximal; by Lemma 3 and Proposition 4 the same holds for clique inequalities with respect to $P_k(G)$.

Not all valid inequalities for $P_k(G)$ can be derived from $P(G)$. As noted above, the maximum k -colorable subgraph problem is a stable set problem in the product graph $G \times K_k$. Thus, one can obtain inequalities from this (larger) stable set problem as well. It is easy to see that the only cliques in $G \times K_k$ arise from cliques in G or from each K_k ; thus, the product graph does not give new clique inequalities. However, in $G \times K_k$ new odd holes can appear. Hence, odd hole inequalities for $P_k(G)$ exist that are not trivially lifted inequalities from $P(G)$.

2.2. Cases of complete linear descriptions of $P_k(G)$

Using results in the literature on the perfectness of product graphs, one can characterize graphs for which the LP-relaxation of $IP_k(G)$ together with clique inequalities gives a complete description of $P_k(G)$. We provide this section for completeness and refer to Grötschel et al. [27] for a discussion of perfect graphs.

We need the following classes of perfect graphs. A graph is a *TDF graph* (or $(C_{n+4}, \text{diamond})$ -free graph), if it contains no induced diamond and is triangulated, i.e., the graph does not contain an induced cycle C_n of size $n \geq 4$, see [28]. A *parity graph* has the property that for any pair of nodes u and v , all induced paths between u and v have the same parity, i.e., odd or even length. Olaru and Sachs [29] have shown that parity graphs are perfect.

Theorem 5. *Maximal clique, packing, and non-negativity inequalities provide a complete description of $P_k(G)$ if and only if*

- for $k = 1$, G is a perfect graph,
- for $k = 2$, G is a parity graph, or
- for $k > 3$, G is a TDF graph.

Proof. For $k = 1$, the result follows from the classical characterization of the stable set polytope for perfect graphs by Fulkerson [30] and Chvatal [31].

Recall that, for $k \geq 2$, $G \times K_k$ does not contain cliques other than the ones induced by the packing inequalities (i.e., maximal cliques in K_k) or the cliques in G . For $k = 2$, De Werra and Hertz [32] showed that $G \times K_k$ is perfect, if and only if, G is a parity graph. Moreover, for $k > 2$, they showed that $G \times K_k$ is perfect, if and only if, G is a TDF graph. \square

3. Symmetry handling and LP-bounds

Despite the knowledge we have about $P_k(G)$, the corresponding IP-formulation still suffers from symmetry. We therefore later propose to combine $P_k(G)$ with a polytope that handles symmetries. Let us first define what we mean by symmetry.

Definition 3. A *symmetry* of an integer program is a permutation of the variables that maps feasible solutions to feasible solutions with the same objective function.

The symmetries define the *symmetry group* of an IP.

The unweighted version of $(IP_k(G))$ exhibits two basic types of symmetries: graph and color symmetries. Color symmetries arise by the possibility of (arbitrarily) permuting the colors. This corresponds to an operation of the symmetric group on the columns of $(IP_k(G))$. Graph symmetries arise from the fact that the underlying graph may have non-trivial automorphisms. For a study of graph symmetry handling, we refer the reader to [3]—in this paper, we concentrate on color symmetries.

3.1. Orbitopes

In order to handle symmetries such as the color symmetries of the maximum k -colorable subgraph problem, orbitopes were introduced in [2]. In the following, we summarize those results on orbitopes that we need for the exposition of our results. In order to avoid trivial cases, we will assume for the rest of this paper that $n > k > 1$.

We denote by $\mathcal{M}_{n,k} := \{x \in \{0, 1\}^{[n] \times [k]} : x(\text{row}_i) \leq 1 \text{ for all } i \in [n]\}$, the 0/1-matrices with row-sum at most 1. Let $<$ be the lexicographic ordering of $\mathcal{M}_{n,k}$ with respect to a row-wise flattening of x , i.e., the ordering $(1, 1) < (1, 2) < \dots < (1, k) < (2, 1) < (2, 2) < \dots < (2, k) < \dots < (n, k)$ of matrix positions. We have $A < B$ with $A = (a_{ij}), B = (b_{ij}) \in \mathcal{M}_{n,k}$ if and only if $a_{k\ell} < b_{k\ell}$, where (k, ℓ) is the first position with respect to the ordering where A and B differ. Let \mathfrak{S}_k be the symmetric group on $[k]$. Then $\mathcal{M}_{n,k}^{\max}$ is the set of matrices in $\mathcal{M}_{n,k}$ that are maximal with respect to $<$ within their orbits under the group action of \mathfrak{S}_k . It is not hard to see that a matrix is in $\mathcal{M}_{n,k}^{\max}$ if and only if its columns are sorted lexicographically. We define the *packing orbitope* (with respect to \mathfrak{S}_k) as

$$O_{n,k} := \text{conv}(\mathcal{M}_{n,k}^{\max}).$$

In [2], other types of orbitopes are investigated. Since we only consider packing orbitopes with respect to \mathfrak{S}_k , in the following, we refer to them simply as *orbitopes*. The paper [2] shows that the linear optimization problem over orbitopes can be solved in $O(n^2k)$ time. Moreover, a complete non-redundant linear description of orbitopes by exponentially many linear inequalities is derived. We need further notation for the exposition of this result.

Because of the lexicographic ordering, the equations $x_{ij} = 0$ for all $i < j$ are valid for orbitopes. We therefore define the index set

$$\mathcal{I}_{nk} := \{(i, j) \in [n] \times [k] : i \geq j\}$$

of the remaining variables. Using $k(i) := \min\{i, k\}$, we adjust the definitions of $\text{row}_i := \{(i, 1), (i, 2), \dots, (i, k(i))\}$ and $\text{col}_j := \{(j, j), (j+1, j), \dots, (n, j)\}$. For $(i, j) \in \mathcal{I}_{nk}$, we denote by

$$\text{col}(i, j) := \{(j, j), (j+1, j), \dots, (i-1, j), (i, j)\} \subseteq \mathcal{I}_{nk}$$

the column up to row i . For elements in \mathcal{I}_{nk} , we introduce a system of “diagonal” coordinates in the following way:

$$\langle \eta, j \rangle := (j + \eta - 1, j) \quad \text{for } j \in [k], 1 \leq \eta \leq n - j + 1.$$

Thus, η determines the index of the diagonal containing $(j + \eta - 1, j)$.

For a given $(i, j) = \langle \eta, j \rangle \in \mathcal{I}_{nk}$, with $i > 1$ and $j > 1$, define $B = \{(i, j), (i, j+1), \dots, (i, k(i))\}$ to be the *bar* with leader (i, j) . The inequality

$$x(B) - x(\text{col}(i-1, j-1)) \leq 0,$$

is a so-called *column inequality*. A point $x \in \{0, 1\}^{\mathcal{I}_{nk}}$ is contained in the orbitope if and only if x satisfies all packing inequalities and all column inequalities, see [2]. To obtain the complete linear description, we need the following generalization of column inequalities.

Consider a *shifted column*

$$S = \{\langle 1, c_1 \rangle, \langle 2, c_2 \rangle, \dots, \langle \eta, c_\eta \rangle\} \subseteq \mathcal{I}_{nk}$$

with $c_1 \leq c_2 \leq \dots \leq c_\eta$. It is called a *shifting* of each of the columns $\text{col}(\eta, c_\eta)$, $\text{col}(\eta, c_\eta + 1)$, \dots , $\text{col}(\eta, k)$. We obtain the corresponding *shifted column inequality* (SCI)

$$x(B) - x(S) \leq 0.$$

An example of an SCI appears on the left-hand side of Fig. 12.

SCIs can be separated in linear time. The orbitope is completely described by packing inequalities, non-negativity inequalities, and SCIs [2]. Faenza and Kaibel [10] provide an alternative, elegant proof of this result.

3.2. LP-bounds

In this section, we study the quality of the upper bound obtained via the unweighted LP-relaxation ($\text{LP}_k^1(G)$) of ($\text{IP}_k(G)$), i.e., we relax all integrality conditions (4) on the variables and use $w(v) = 1$ for all $v \in V$. We will then investigate whether the bound improves if we add equations $x_{vj} = 0$ for all $v < j$ and SCIs in order to handle symmetry. Let $\text{opt}(\cdot)$ be the value of some LP/IP-formulation.

Proposition 6. $\text{opt}(\text{LP}_k^1(G)) = n$.

Proof. A solution with $x_{ij} = \frac{1}{k}$ for every $(i, j) \in V \times [k]$ has objective n and satisfies all inequalities independent of the graph. Moreover, n is clearly an upper bound on $\text{opt}(\text{LP}_k^1(n))$ (add all packing inequalities (3)). \square

Remark 7. The solution in the previous proof lies in the relative interior of the face defined by all packing inequalities. It corresponds to the barycenter of the orbit of a (hypothetical) solution that colors all nodes.

Remark 8. Since $\text{opt}(\text{IP}_k(K_n)) = k$ (for unit weights), the above result shows that the gap between the value of the LP-relaxation and the optimal value can be arbitrarily large.

It is natural to investigate the strength of the following unweighted LP-relaxation that arises by adding a full description of the corresponding orbitope via SCIs:

$$\begin{aligned}
 (\text{OLP}_k^1(G)) \quad & \max \sum_{v \in V} \sum_{j \in [k]} x_{vj} \\
 & x_{uj} + x_{vj} \leq 1 \quad \forall \{u, v\} \in E, j \in [k] \\
 & x(\text{row}_v) \leq 1 \quad \forall v \in V \\
 & x(B) - x(S) \leq 0 \quad \forall \text{ bars } B \text{ and corr. SCs } S \\
 & x_{vj} = 0 \quad \forall v \in V, j \in [k] \text{ with } v < j \\
 & x_{vj} \in [0, 1] \quad \forall v \in V, j \in [k].
 \end{aligned}$$

We obtain the following bound on the value of this formulation.

Proposition 9. $\text{opt}(\text{OLP}_k^1(G)) \geq n - \frac{1}{2^{k-1}}$.

Proof. We construct a feasible solution x of ($\text{OLP}_k^1(G)$) with objective value equal to $n - \frac{1}{2^{k-1}}$ as follows:

$$x_{ij} := \begin{cases} 1 - \frac{1}{2^{k-1}} & \text{if } (i, j) = (1, 1) \text{ or } (i, j) = (2, 2) \\ \frac{1}{2^{k-1}} & \text{if } i \geq 2 \text{ and } j = 1 \\ \frac{1}{2^{k-j+1}} & \text{if } i \geq 3 \text{ and } 2 \leq j < k(i) \\ 1 - \frac{1}{2^{k-j+1}} & \text{if } i \geq 3 \text{ and } j = k(i) \\ 0 & \text{otherwise.} \end{cases}$$

Fig. 2 contains an illustration of the construction. It is not hard to see that for $i \geq 2$, the sum of the i th row is 1, while $x_{11} = 1 - \frac{1}{2^{k-1}}$. Thus the objective value is $n - \frac{1}{2^{k-1}}$ as claimed. Moreover, each entry off the diagonal has value $\leq \frac{1}{2}$ and the sum of any two entries in a column is at most 1. Thus, all edge inequalities are satisfied.

We next show that x fulfills all shifted column inequalities. First observe that $x_{ij} < 1$ for $j > 1$ and $x(\text{col}(i-1, j-1)) \geq 1$ for $i \neq j$, $i, j > 1$. This is also true for shiftings of $\text{col}(i-1, j-1)$. If $i = j$, then the shifted column inequalities hold trivially because $x_{ii} \leq x_{\ell\ell}$ for $i > \ell$. \square

	1	2	3	...	j	...	k	
1	$1 - \frac{1}{2^{k-1}}$							
2	$\frac{1}{2^{k-1}}$	$1 - \frac{1}{2^{k-1}}$						$\Sigma = 1$
3	\vdots	$\frac{1}{2^{k-1}}$	$1 - \frac{1}{2^{k-2}}$	\ddots				$\Sigma = 1$
\vdots		\vdots	$\frac{1}{2^{k-2}}$		$1 - \frac{1}{2^{k-j+1}}$	\ddots		$\Sigma = 1$
\vdots			\vdots	\vdots			$\frac{1}{2}$	$\Sigma = 1$
\vdots					\vdots		\vdots	\vdots
n	$\frac{1}{2^{k-1}}$	$\frac{1}{2^{k-1}}$	$\frac{1}{2^{k-2}}$		$\frac{1}{2^{k-j+1}}$		$\frac{1}{2}$	$\Sigma = 1$

Fig. 2. The solution of $(\text{OLP}_k^1(G))$ as constructed in the proof of Proposition 9 with objective value $n - \frac{1}{2^{k-1}}$.

Proposition 9 shows that the possible improvement obtained by adding a complete orbitopal description is small; in fact, it decreases as k increases. The slight improvement is due to the fixing of variables on the top right. Thus, the most primitive form of symmetry handling by fixing variables is in general as strong as its most sophisticated form via exponentially many inequalities. Moreover, the gap to the optimal integral value remains arbitrarily large.

Thus, in order to improve the value of the LP-relaxation, we need to take the structure of the graph into account. Clearly, adding cutting planes like clique inequalities will often improve the LP-bound. However, relevant instances are known in which the clique number is 2, i.e., clique inequalities will not improve the bound. Another way to improve the LP-bound beyond the basic formulation is by inequalities that combine symmetry handling with the structure of the graph. Such inequalities will be investigated in the next section.

4. Combining k -colored subgraph polytopes with orbitopes

In the following, we study the convex hull of the intersection of the orbitope with the k -colored subgraph polytope, i.e., we define

$$\text{OP}_k(G) := \text{conv}(\{x \in P_k(G) \cap \mathcal{M}_{n,k}^{\max}\}),$$

which clearly is a 0/1-polytope. Note that all facets of $P_k(G)$ and $\text{O}_{n,k}$ remain valid for $\text{OP}_k(G)$. This section is devoted to conditions under which facets remain facets or can be modified to yield facets.

The polytope $\text{OP}_k(G)$ adds orbitope symmetry breaking inequalities to the integer programming formulation $(\text{IP}_k(G))$. In this way we obtain combinations of symmetry handling with problem-specific structure.

We obtain the following basic result on the dimension and non-negativity constraints.

Proposition 10.

- We have $\dim(\text{OP}_k(G)) = |\mathcal{I}_{nk}|$, i.e., $\text{OP}_k(G)$ is full-dimensional.
- Let $\langle \eta, j \rangle \in \mathcal{I}_{nk}$. The non-negativity inequality $x_{\langle \eta, j \rangle} \geq 0$ defines a facet of $\text{OP}_k(G)$, if and only if, $\eta \neq 1$ or $\eta = 1$ and $j = k$. If $\eta = 1$, the faces defined by $x_{\langle \eta, j \rangle} \geq 0$ for $1 \leq j < k$ are contained in the facet defined by $x_{\langle 1, k \rangle} \geq 0$.

Proof. The proof is elementary, but shows the techniques needed in the following. For $\langle \sigma, t \rangle = (s, t) \in \mathcal{I}_{nk}$, we define

$$\text{diag}^{\leq} \langle \sigma, t \rangle = \text{diag}^{\leq}(s, t) := \{\langle \sigma, 1 \rangle, \langle \sigma, 2 \rangle, \dots, \langle \sigma, t \rangle\}$$

as the subset of indices of a diagonal that starts at $\langle \sigma, 1 \rangle$ and ends at $\langle \sigma, t \rangle$. We define the matrix $W^{\leq \langle \sigma, t \rangle} = W^{\leq(s, t)}$ as the incidence matrix of the set $\text{diag}^{\leq} \langle \sigma, t \rangle$. Any such matrix corresponds to a colored subgraph with lexicographically ordered columns.

For the proof of the dimension, we note that for $\langle \sigma, t \rangle \in \mathcal{I}_{nk}$, we have $W^{\leq \langle \sigma, t \rangle} \in \text{OP}_k(G)$. Together with $\mathbf{0} \in \text{OP}_k(G)$, they form $|\mathcal{I}_{nk}| + 1$ affinely independent matrices.

Consider non-negativity inequalities with $\eta > 1$ first. For $\langle \sigma, t \rangle \in \mathcal{I}_{nk}$ with $\langle \sigma, t \rangle \neq \langle \eta, j \rangle$, we define the following matrix as depicted in Fig. 3:

$$V^{(\sigma, t)} := \begin{cases} W^{\leq \langle \sigma, t \rangle} & \text{if } \sigma \neq \eta & \text{(a)} \\ W^{\leq \langle \sigma, t \rangle} & \text{if } \sigma = \eta \text{ and } t < j & \text{(b)} \\ W^{\leq \langle \sigma-1, j \rangle} + W^{\leq \langle \sigma, t \rangle} - W^{\leq \langle \sigma, j \rangle} & \text{if } \sigma = \eta \text{ and } t > j. & \text{(c)} \end{cases} \quad (7)$$

In case (7)(c) we use the assumption that $\eta \neq 1$. Additionally, we define $V^{(\eta, t)} = \mathbf{0}$. Each matrix $V^{(\sigma, t)} \in \text{OP}_k(G)$ fulfills inequality $x_{\langle \eta, j \rangle} \geq 0$ with equality. It is easy to see that these matrices form $|\mathcal{I}_{nk}|$ many affinely independent matrices, proving that $x_{\langle \eta, j \rangle} \geq 0$ defines a facet.

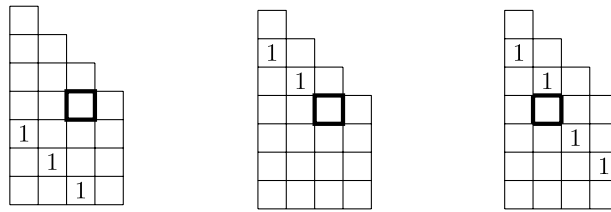


Fig. 3. Matrices $V^{(\sigma,t)}$ in the proof of Proposition 10. The index of the non-zero coefficient $\langle \eta, j \rangle$ of the non-negativity inequality under consideration is highlighted. Left: case (7)(a): $V^{(5,3)}$. Middle: case (7)(b): $V^{(2,2)}$. Right: case (7)(c): $V^{(3,4)}$.

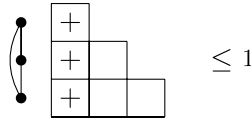


Fig. 4. For K_3 and $k = 3$, the clique inequality for color 1 dominates all packing inequalities.

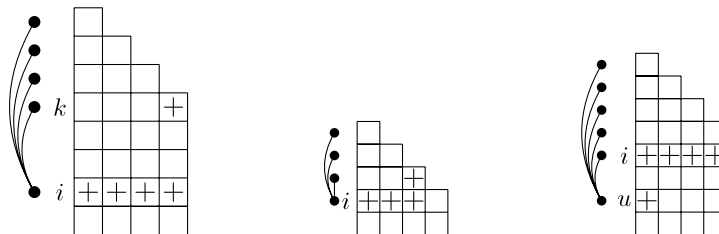


Fig. 5. Proof of Theorem 13: inequalities that dominate the packing inequality. Left: node $i > k$ is adjacent to all nodes in $[k]$. Middle: node $i \leq k$ is adjacent to all nodes in $[i - 1]$. Right: node $u > i$ is adjacent to all nodes in $[i]$.

Consider $\eta = 1$ next. Any matrix that fulfills $x_{\langle 1,j \rangle} \geq 0, j < k$, with equality also fulfills $x_{\langle 1,k \rangle} \geq 0$ with equality, since it must have 0-entries in positions $\langle 1, t \rangle$ with $j < t \leq k$ due to the lexicographic ordering of the columns. We can choose matrices $W^{\leq(\sigma,t)}$ for $\langle \sigma, t \rangle \neq \langle 1, k \rangle$ and $\mathbf{0}$ to prove that $x_{\langle 1,k \rangle} \geq 0$ defines a facet. \square

Remark 11. Note that $\text{OP}_k(G)$ is not monotone. Hence, the results of Hammer et al. [25] cannot be applied. Indeed, we will see non-trivial homogeneous inequalities and inequalities with positive and negative coefficients.

4.1. Packing inequalities

The following example illustrates that, in contrast to $\text{O}_{n,k}$ and $\text{P}_k(G)$, packing inequalities do not always define facets for $\text{OP}_k(G)$.

Example 12. Any packing inequality for $\text{OP}_3(K_3)$ is dominated by the clique inequality $x_{11} + x_{21} + x_{31} \leq 1$, see Fig. 4. Due to the lexicographic ordering, any solution with an entry 1 that is not in the first column must have a 1 in the first column. Hence, the above clique inequality holds with equality. Thus, in $\text{OP}_3(K_3)$ no packing inequality defines a facet.

Theorem 13. The packing inequality

$$x(\text{row}_i) \leq 1$$

defines a facet of $\text{OP}_k(G)$, if and only if, the following conditions hold.

- (1) There exists a node $v \in [k(i)]$ such that $v \notin \overline{\Gamma}(i)$, and
- (2) for every node $u \in \{i + 1, i + 2, \dots, n\}$ there exists a node $w_u \in [i]$ such that $w_u \notin \Gamma(u)$.

Proof. “ \Rightarrow ” We show that the conditions are necessary. We first assume for the sake of contradiction that $[k(i)] \subseteq \overline{\Gamma}(i)$. If $i > k$, consider the inequality

$$x(\text{row}_i) + x_{kk} \leq 1, \tag{8}$$

which is depicted on the left-hand side of Fig. 5. Let us show the validity of Inequality (8), which contradicts the assumption that the packing inequality is facet-defining. Any $\tilde{x} \in \text{OP}_k(G)$ with $\tilde{x}_{kk} = 1$ must have $\tilde{x}_{it} = 1$ for $t \in [k]$ due to the lexicographic ordering of the columns. Due to the adjacency of i to any node in $[k]$, it follows that $\tilde{x}(\text{row}_i) = 0$, so Inequality

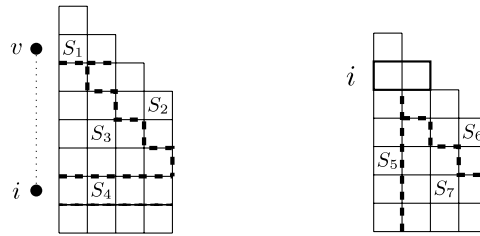


Fig. 6. The sets used in the proof of [Theorem 13](#). *Left:* the sets S_1 – S_4 on or above row i . *Right:* the sets S_5 – S_7 below row i .

(8) is valid. Inequality (8) dominates the packing inequality for row i , since $W^{\leq(k,k)}$ fulfills (8) with equality, but not the packing inequality.

If $i \leq k$, consider

$$\sum_{j=1}^{i-1} x_{ij} + x_{i-1,i-1} \leq 1. \quad (9)$$

The non-zero coefficients in Inequality (9) are shown in the middle of [Fig. 5](#). Let us show the validity of Inequality (9). Any $\tilde{x} \in \text{OP}_k(G)$ with $\tilde{x}_{i-1,i-1} = 1$ has $\tilde{x}_{tt} = 1$ for $t \in [i-1]$ due to the lexicographic ordering of the columns. Due to the adjacency of i to any node in $[i-1]$, it follows that $\tilde{x}(\text{row}_i) = 0$, so Inequality (8) is valid. Note that even though position (i, i) does not appear in (9), a feasible solution \tilde{x} with $\tilde{x}_{ii} = 1$ fulfills Inequality (9) with equality, since this matrix must have 1s along the main diagonal due to the lexicographic ordering. Moreover, matrix $W^{\leq(i-1,i-1)}$ fulfills (9) with equality, but does not fulfill the packing inequality with equality.

For handling the second condition, we assume that there exist a node $u > i$ such that $[i] \subseteq \Gamma(u)$. In this case, consider inequality

$$\sum_{j=1}^{k(i)} x_{ij} + x_{u1} \leq 1, \quad (10)$$

which clearly dominates the packing inequality for row i ; see the right of [Fig. 5](#) for an illustration. The validity can be seen as follows. Any point \tilde{x} with $\tilde{x}_{i,1} = 1$ and $\tilde{x}_{u,1} = 1$ violates an edge inequality. Moreover, if for any feasible solution $\tilde{x}_{u,1} = 1$, then it follows that $\tilde{x}_{1,1} = \tilde{x}_{2,1} = \dots = \tilde{x}_{i,1} = 0$ because of the edge inequalities. Thus, due to the lexicographic ordering, $\tilde{x}(\text{row}_i) = 0$.

“ \Leftarrow ” We show that the conditions are sufficient. Let \mathcal{V} be the set of vertices of $\text{OP}_k(G)$ that satisfy the packing inequality for row i with equality. Define $\mathcal{L} := \text{lin}(\mathcal{V})$ as the linear span of the elements in \mathcal{V} . We shall show that the unit matrix E^{st} with $(s, t) \in \mathcal{I}_{nk}$ is contained in \mathcal{L} . It follows that \mathcal{L} contains $|\mathcal{I}_{nk}|$ linearly independent points and since $\mathbf{0} \notin \mathcal{V}$, we have $\dim(\text{aff}(\mathcal{V})) = |\mathcal{I}_{nk}| - 1$. Hence, the packing inequality for row i defines a facet of $\text{OP}_k(G)$.

The proof relies on the fact that there exists a node $v < i$ such that $v \notin \overline{\Gamma}(i)$. In order to show that $E^{st} \in \mathcal{L}$ for all $(s, t) \in \mathcal{I}_{nk}$, we partition the set \mathcal{I}_{nk} into the following seven sets:

$$\begin{aligned} S_1 &:= \{(s, t) \in \mathcal{I}_{nk} : s \leq v\} \\ S_2 &:= \{(\sigma, t) = (s, t) \in \mathcal{I}_{nk} : v < s < i, \sigma \leq v\} \\ S_3 &:= \{(\sigma, t) = (s, t) \in \mathcal{I}_{nk} : v < s < i, \sigma > v\} \\ S_4 &:= \text{row}_i \\ S_5 &:= \{(s, t) : t = 1, s > i\} \\ S_6 &:= \{(s, t) = (\sigma, t) : s > i, \sigma \leq i\} \\ S_7 &:= \{(s, t) = (\sigma, t) : s > i, \sigma > i\}. \end{aligned}$$

[Fig. 6](#) contains a graphic depiction of the sets. On the left-hand side, we have the sets S_1 , S_2 , S_3 , and S_4 corresponding to the parts in or above row i . The right-hand side shows the sets S_5 , S_6 , and S_7 below row i . The following seven claims will deal with each set in turn.

Claim 1. For all $(s, t) \in S_1$, $E^{st} \in \mathcal{L}$.

Proof. Consider the case $s = v$ first. Assume $v, t > 1$. We construct a linear combination of vertices of $\text{OP}_k(G)$ that yields the unit matrix E^{st} . Each vertex of $\text{OP}_k(G)$ in the following linear combination fulfills the packing inequality for row i with equality:

$$E^{st} = E^{vt} = (W^{\leq(v,t)} + E^{it}) \quad (11)$$

$$- (W^{\leq(v-1,t-1)} + E^{it}). \quad (12)$$

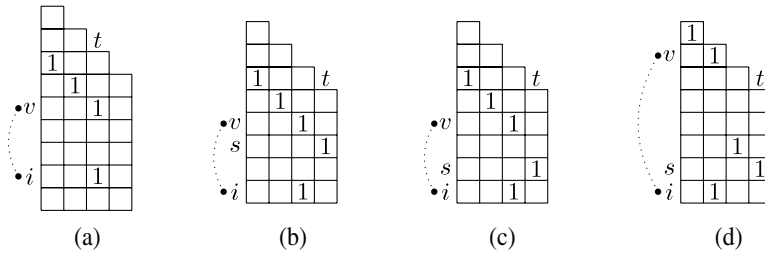


Fig. 7. Matrices in the proof of Theorem 13 for the sets above row_i . (a): term (11) of Claim 1. (b): term (19) of Claim 2. (c): term (20) of Claim 3. (d): term (22) of Claim 3.

Fig. 7(a) contains a depiction of term (11). Both (11) and (12) form vertices of $\text{OP}_k(G)$, since they are 0/1 – matrices and have lexicographically ordered columns; in term (11) we use the assumption that $\{v, i\} \notin E$, so no edge inequality is violated. By definition of the matrices $W^{\leq(s,t)}$ we have $E^{vt} = W^{\leq(v,t)} - W^{\leq(v-1,t-1)}$.

Consider $v = 1$ or $t = 1$. Note that $t = 1$ follows from $v = 1$. We use $E^{vt} = (E^{vt} + E^{it}) - E^{it}$ as the linear combination of vertices of $\text{OP}_k(G)$.

Consider $1 < s < v$ and $t \neq 1$. Then, the linear combination is:

$$E^{st} = (W^{\leq(s,t)} + E^{i,t+1}) \quad (13)$$

$$- (W^{\leq(s-1,t-1)} + E^{i,t+1} + E^{vt}) \quad (14)$$

$$+ E^{vt}. \quad (15)$$

Term (15) is not a vertex of $\text{OP}_k(G)$ (it does not have lexicographically ordered columns), but we have already proved it to be contained in \mathcal{L} . For (13) and (14) we use the following. For $k < i$, we use that $v \leq k$, so we have $t + 1 \leq k$ since $s < v$. For $i = k$, we use that $v < i$, so we have $t + 1 < k$ as well. Thus $E^{st} \in \mathcal{L}$ in this case.

For $s = 1$ or $t = 1$, the linear combination is

$$E^{st} = (E^{st} + E^{v,t+1} + E^{i,t+1}) \quad (16)$$

$$- (E^{i,t+1} + E^{vt}) \quad (17)$$

$$- (E^{v,t+1} - E^{vt}). \quad (18)$$

Note that if $s = 1$ then $t = 1$, i.e., in any case $t = 1$. We have proved already that both summands in (18) are in \mathcal{L} . Since we have $k \geq 2$, for $t = 1$ we have $t + 1 \in [k]$ and term (17) is a vertex of $\text{OP}_k(G)$. In term (16), we use that $\{v, i\} \notin E$. \square

Claim 2. For all $(s, t) = \langle \sigma, t \rangle \in S_2$, $E^{st} \in \mathcal{L}$.

Proof. For $(s, t) = \langle \sigma, t \rangle \in S_2$, we have

$$\emptyset \neq \text{diag}^{\leq} \langle \sigma, t \rangle \cap \text{row}_v = \{\langle \sigma, v - \sigma + 1 \rangle\}$$

and $t \geq 2$ by definition of S_2 . Hence, the linear combination for E^{st} is:

$$E^{st} = (W^{\leq(s,t)} + E^{i,v-\sigma+1}) \quad (19)$$

$$- (W^{\leq(s-1,t-1)} + E^{i,v-\sigma+1}).$$

We depict the matrix in (19) in Fig. 7(b). Both terms in parentheses are in \mathcal{V} , where we have used that $\{v, i\} \notin E$. \square

For the proof of the next claim, we need further notation. Let $\langle \sigma, t \rangle \in \mathcal{I}_{nk}$. We define

$$\text{diag}^{\leq} \langle \sigma, t \rangle|_j := \{\langle \sigma, j + 1 \rangle, \langle \sigma, j + 2 \rangle, \dots, \langle \sigma, t \rangle\}$$

and let $W^{\leq \langle \sigma, t \rangle|_j}$ be the corresponding incidence matrix.

Claim 3. For all $(s, t) = \langle \sigma, t \rangle \in S_3$, $E^{st} \in \mathcal{L}$.

Proof. Consider $t = 1$ first. The linear combination is:

$$E^{s1} = (E^{s1} + E^{i2}) - (E^{v1} + E^{i2}) + E^{v1},$$

where we use that $k \geq 2$. As shown in Claim 1, we have $E^{v1} \in \mathcal{L}$.

Consider $t > 1$ with $t - 1 \leq k(v)$. Then

$$E^{st} = (W^{\leq(v,t-1)} + E^{st} + E^{i,t-1}) \quad (20)$$

$$- (W^{\leq(v,t-1)} + E^{i,t-1}). \quad (21)$$

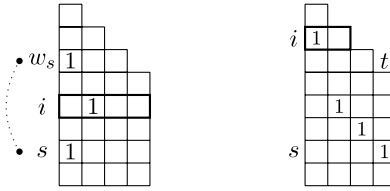


Fig. 8. Left: term (24) of Claim 5. Right: term (26) of Claim 7.

We depict (20) in Fig. 7(c), where we use $t > 1$. Since $t - 1 \leq k(v)$, we know that $(v, t - 1) \in \text{row}_v$. In (21), we use that $\{v, i\} \notin E$.

For the case that $t - 1 > k(v)$, the linear combination is:

$$E^{st} = (W^{\leq(v, k(v))} + E^{i, k(v)} + W^{\leq(\sigma, t)|_{k(v)}} \quad (22)$$

$$- (W^{\leq(\sigma, t-1)|_{k(v)}} + W^{\leq(v, k(v))} + E^{i, k(v)}). \quad (23)$$

We depict (22) in Fig. 7(d). Matrix (22) has lexicographically ordered columns by definition of S_3 , and the same is true for (23). We use the assumption that node $\{v, i\} \notin E$ in both terms. \square

Claim 4. For all $(s, t) = \langle \sigma, t \rangle \in \text{row}_i = S_4$, $E^{st} \in \mathcal{L}$.

Proof. For $t = 1$, the claim is trivially true since E^{s1} with $s = i$ is a vertex of $\text{OP}_k(G)$ that fulfills the packing inequality for row i with equality.

For $1 < t \leq k(i)$, we use $E^{(\sigma, t)} = W^{\leq(\sigma, t)} - W^{\leq(\sigma, t-1)}$, where we use the above claims since $\langle \sigma, t - 1 \rangle$ is contained in sets S_1 , S_2 , or S_3 . Hence, $W^{\leq(\sigma, t-1)}$ is contained in \mathcal{L} . \square

In the next claims, we rely on the hypothesis that for every node $u > i$, a node $w_u \in [i]$ exists with $w_u \notin \Gamma(u)$.

Claim 5. For $(s, t) \in S_5$, $E^{st} \in \mathcal{L}$.

Proof. By hypothesis, for every node $s > i$, there exists a node w_s with $\{w_s, s\} \notin E$. If $w_s < i$, then we use:

$$E^{s1} = (E^{s1} + E^{w_s, 1} + E^{i2}) \quad (24)$$

$$- (E^{w_s, 1} + E^{i2}). \quad (25)$$

We have depicted (24) on the left-hand side of Fig. 8. Term (24) does not violate an edge inequality by assumption. If $w_s = i$, then the linear combination is $E^{s1} = (E^{s1} + E^{i1}) - E^{i1}$. \square

Claim 6. For $(s, t) \in S_6$, $E^{st} \in \mathcal{L}$.

Proof. We note that for $(s, t) \in S_6$, $\text{diag}^{\leq}(s, t) \cap \text{row}_i \neq \emptyset$. Hence, $E^{st} = W^{\leq(s, t)} - W^{\leq(s-1, t-1)}$. Note that if $S_6 \neq \emptyset$, then $t > 1$. \square

For the proof of the next claim, we need the following notation. Let

$$\text{diag}^{\geq}(s, t) := \{\langle \sigma, t \rangle, \langle \sigma, t + 1 \rangle, \dots, \langle \sigma, k \rangle\}$$

and

$$\text{diag}^{\geq}(s, t)|_c := \{\langle \sigma, t \rangle, \langle \sigma, t + 1 \rangle, \dots, \langle \sigma, c - 1 \rangle\}.$$

We define $W^{\geq(s, t)}$ and $W^{\geq(s, t)|_c}$ to be the incidence matrices of $\text{diag}^{\geq}(s, t)$ and $\text{diag}^{\geq}(s, t)|_c$, respectively.

Claim 7. For $(s, t) = \langle \sigma, t \rangle \in S_7$, $E^{st} \in \mathcal{L}$.

Proof. The following linear combination gives E^{st} :

$$E^{st} = (W^{\geq(\sigma, 2)|_{t+1}} + E^{i, 1}) \quad (26)$$

$$- (W^{\geq(\sigma, 2)|_t} + E^{i, 1}), \quad (27)$$

see the right-hand side of Fig. 8 for a depiction of (26). \square

In total, we proved that for all $(s, t) \in \mathcal{I}_{nk}$, we have $E^{st} \in \mathcal{L}$ which terminates the proof. \square

Note that the statement of the previous theorem takes both the combinatorial structure of the underlying graph and the labeling of the nodes of the graph into account.

Note. Our subsequent results on the facet-defining properties of inequalities have proofs that rely on similar techniques as in the proof of [Theorem 13](#) above. We therefore omit these proofs in the present paper. For full details, we refer the reader to [\[33\]](#).

As we have seen, packing inequalities do not always define facets of $\text{OP}_k(G)$. However, under some circumstances they can be combined with inequalities for the stable set problem to yield facets of $\text{OP}_k(G)$. We have the following general validity statement.

Proposition 14. *Let $\alpha^T y \leq \beta$ be a non-trivial valid inequality for $P(G)$ with integral coefficients. Let $W := \{v \in V : \alpha_v \neq 0\}$, and let $w = \max(W)$. Assume that $\Gamma(w) \supseteq \{1, \dots, u-1\}$, where $u = \max(W \setminus \{w\})$. Then,*

$$\sum_{t=1}^{j-1} x_{wt} + \sum_{v \in W} \alpha_v x_{vj} \leq \beta \quad (28)$$

is valid for $\text{OP}_k(G)$ for each $j \leq \min(W, k(w))$.

Proof. If $j = 1$, then the inequality is clearly valid. Thus, we assume that $j > 1$ in the following.

Because of the packing inequalities, the first sum is at most 1. Thus, the inequality is valid for each integral point $\tilde{x} \in \text{OP}_k(G)$ that satisfies

$$\sum_{v \in W} \alpha_v \tilde{x}_{vj} < \beta.$$

Now assume that

$$\sum_{v \in W} \alpha_v \tilde{x}_{vj} = \beta.$$

Since $\alpha^T y \leq \beta$ is a non-trivial inequality, we have $\beta > 0$ and $\alpha \geq 0$, see [Remark 2](#). Hence, there exists $v \in W$ with $\tilde{x}_{vj} = 1$. If $v = w$, then the packing inequality for row w yields that the first sum in (28) is 0. Thus, inequality (28) holds. Otherwise, let $\langle \eta, j \rangle = \langle v, j \rangle$. By the lexicographic ordering, \tilde{x} contains 1s in the diagonal $\text{diag}^{\leq}(\eta, j-1)$ or above it. Since by the assumption there are edges between w and each node in $[v-1] \subseteq [u-1]$, the first sum has to be 0, proving validity. \square

In the special case in which $\alpha^T y \leq \beta$ is a clique inequality, i.e., $C = W$ is a clique, we call the corresponding Inequality (28) *packing-clique inequality*. We next provide a characterization of the cases in which packing-clique inequalities define facets. We first give the result for $j \in C$. Proofs appear in [\[33\]](#).

Theorem 15. *Let $(i, j) \in \mathcal{I}_{nk}$ with $j < i$, let $\Gamma(i) \supseteq [i-1]$, and let $C \subseteq \{j, \dots, i\}$ be a clique such that $i = \max(C)$ and $j \in C$. The packing-clique inequality*

$$\sum_{t=1}^{j-1} x_{it} + x(C \times \{j\}) \leq 1 \quad (29)$$

defines a facet of $\text{OP}_k(G)$ if and only if the following conditions hold:

- (1) C is maximal in the subgraph $G[j, j+1, \dots, i]$;
- (2) if $j > 1$, then there exists no clique C' with $C' \supseteq \{j-1, \dots, i-1\}$; and
- (3) for every node $u \in \{i+1, i+2, \dots, n\}$, there exists a node $w_u \in [i]$ such that $w_u \notin \Gamma(u)$.

Remark 16. [Theorem 15](#) shows that maximal clique inequalities do not always define facets for $\text{OP}_k(G)$ – in contrast to $P(G)$ and $P_k(G)$.

The characterization in [Theorem 15](#) is independent of k , while the next case $j \notin C$ depends on k .

Theorem 17. *Let $(i, j) \in \mathcal{I}_{nk}$ with $j < i$, let $\Gamma(i) \supseteq [i-1]$, and let $C \subseteq \{j, \dots, i\}$ be a clique such that $i = \max(C)$ and $j \notin C$. The packing-clique inequality*

$$\sum_{t=1}^{j-1} x_{it} + x(C \times \{j\}) \leq 1 \quad (30)$$

defines a facet of $\text{OP}_k(G)$ if and only if the following conditions hold:

- (1) C is maximal in the subgraph $G[j, j+1, \dots, i]$;
- (2) if $j > 1$, then there exists no clique C' with $C' \supseteq \{j-1, \dots, i-1\}$;
- (3) for every node $u \in \{i+1, i+2, \dots, n\}$, there exists a node $w_u \in [i]$ such that $w_u \notin \Gamma(u)$; and
- (4) the following must hold for $r = \min(C) - 1$ with $(r, j) = (\rho, j)$:
 - For every $\langle \beta, c \rangle = (b, c)$ with $\beta = 1$, $b \in C$, and $j < c \leq k(b)$, there exists a node $v \in C \cap \{b+1, b+2, \dots, i\}$ such that $\langle j, v \rangle \notin E$, and
 - for every $\langle \beta, c \rangle = (b, c)$ with $b \in C$, $1 < \beta \leq \rho$, and $j < c \leq k(b)$, there exists a node $v \in \{j, j+1, \dots, r\}$ with $\langle v, j \rangle = \langle v, j \rangle$ and $v < \beta$ that is not adjacent to at least one node in $C \setminus \{b\}$.

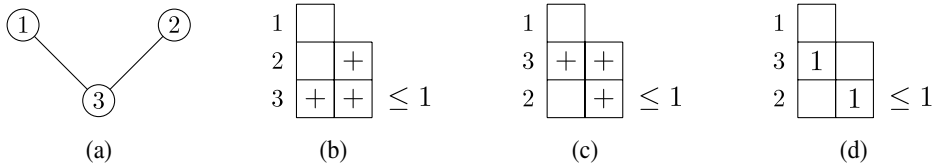


Fig. 9. Example 18: packing-clique inequalities depend on the order of the rows. The numbers on the left-hand side of the rows are node labels.

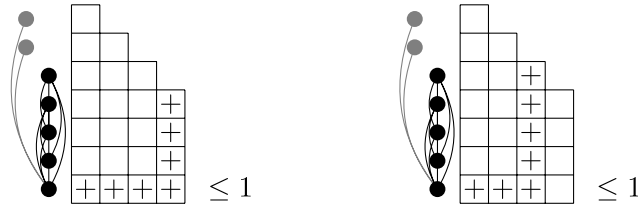


Fig. 10. Example 18: combination of packing with clique inequalities. The clique C is depicted in black nodes and the (additional) neighborhood of $\max(C)$ in gray. The inequality on the right-hand side dominates the one on the left-hand side.

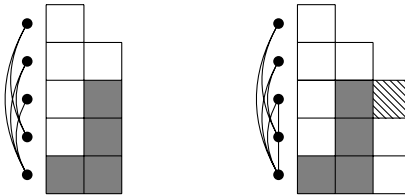


Fig. 11. Example 18: depending on the number of colors, certain packing inequalities may or may not define a facet. Left: for $k = 2$, the packing-clique inequality with non-zero coefficients in gray defines a facet. Right: for $k = 3$, we can enhance the packing-clique inequality with a summand whose index is hatched.

Example 18. We close the discussion of packing-clique inequalities with three explicit examples.

First, Fig. 9 shows that packing-clique inequalities depend on the mapping of nodes to rows of the matrix. Consider the graph shown in Fig. 9(a). By Theorem 15, the packing-clique inequality for $C = \{2, 3\}$, $i = 3$, and $j = 2$ defines a facet for $\text{OP}_2(G)$. We depict this inequality in Fig. 9(b). If we map the nodes to rows as depicted in Fig. 9(c), then the resulting inequality is not valid, since the matrix depicted in Fig. 9(d) violates the inequality.

Second, Fig. 10 shows two packing-clique inequalities. The inequality on the left-hand side is a packing-clique inequality for $C = \{4, 5, 6, 7\}$, $i = 7$, and $j = 4$. It does not define a facet, since it violates Condition (2) of Theorem 15. Indeed, the packing-clique inequality on the right-hand side for $C = \{3, 4, 5, 6, 7\}$, $i = 7$, and $j = 3$ dominates the one on the left-hand side. Thus, again in contrast to $\text{P}(G)$ and $\text{P}_k(G)$, maximal clique and maximal packing-clique inequalities do not always define facets of $\text{OP}_k(G)$.

Finally, Fig. 11 shows an example of a packing-clique inequality for $C = \{3, 4, 5\}$, $i = 5$, and $j = 2$ which, by Theorem 17, defines a facet for $k = 2$ (left). For $k = 3$ (right), Condition (4) of Theorem 17 is violated. Let us briefly show why the depicted inequality on the right is valid. Any $\tilde{x} \in \text{OP}_3(G)$ with $\tilde{x}_{33} = 1$ has $\tilde{x}_{32} = 0$ due to the packing inequality. Furthermore, we must have $\tilde{x}_{22} = \tilde{x}_{11} = 1$ because of the lexicographic ordering of the columns. Since nodes 1 and 2 are adjacent to nodes 4 and 5, none of the other summands in the packing-clique inequality can be 1. Dominance is immediate.

4.2. Shifted column inequalities

Shifted column inequalities define facets of the orbitope in most cases. We investigate conditions under which SCIs define facets of $\text{OP}_k(G)$ and start with the special case of the main diagonal.

Proposition 19. The SCI $x(B) - x(S) \leq 0$ with shifted column $S := \{\langle 1, j \rangle\}$ and bar $B := \{\langle 1, j+1 \rangle\}$ defines a facet of $\text{OP}_k(G)$ for $1 \leq j < k$.

The SCIs in which $S = \{\langle 1, j \rangle\}$ and $B = \{\langle 1, t \rangle\}$ with $j+1 < t \leq k$ are contained in the SCIs with $S = \{\langle 1, \ell \rangle\}$ and $B = \{\langle 1, \ell+1 \rangle\}$ for $j \leq \ell \leq t$.

Proof. If $B = \{\langle 1, j+1 \rangle\}$, then the matrices $W^{\leq(s,t)}$, for all $(s, t) \in \mathcal{I}_{nk} \setminus \{(j, j)\}$, fulfill the SCI with equality. Together with $\mathbf{0}$, we have $|\mathcal{I}_{nk}|$ affinely independent matrices that fulfill the SCI with equality, showing the claim.

The SCI with $S = \{\langle 1, j \rangle\}$ and $B = \{\langle 1, t \rangle\}$ is the sum of the SCIs $x_{\langle 1, j+1 \rangle} - x_{\langle 1, j \rangle} \leq 0, \dots, x_{\langle 1, t+1 \rangle} - x_{\langle 1, t \rangle} \leq 0$. Thus, they do not define facets for $\text{OP}_k(G)$. \square

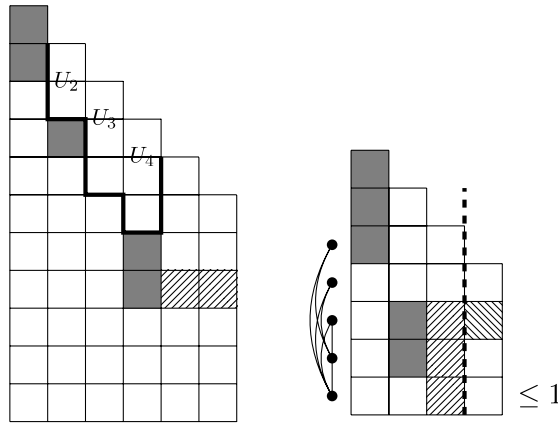


Fig. 12. Left: example for an SCI and the definition of U_2, U_3, U_4 ($U_1 = \emptyset$). Right: the CSCI defines a facet for $k = 3$, but not for $k = 4$. For $k = 4$, the third condition of Theorem 24 is violated and the CSCI is dominated by an enhanced CSCI.

We need some more notation for general SCIs. For $j \in [k]$, consider a shifted column $S = \{\langle 1, c_1 \rangle, \langle 2, c_2 \rangle, \dots, \langle \eta, c_\eta \rangle\}$ with $c_\eta < j$. For column $c \in \{c_1, c_1 + 1, \dots, j - 1\}$, we define

$$\hat{U}_c := \{(\rho, c) : \rho < \delta \text{ for all } \langle \delta, t \rangle \in S \text{ with } c \leq t\},$$

the set of all matrix entries that lie above the diagonals defined by S intersected with column c . The set U_c is defined as the projection on the first coordinate of \hat{U}_c , see the left-hand side of Fig. 12.

Theorem 20. Let $i \in V$ be a node, $j \in \{2, \dots, k(i)\}$, and $\langle \sigma, j \rangle = (i, j)$ such that $\sigma > 1$. The SCI $x(B) - x(S) \leq 0$ with bar $B = \{(i, j), \dots, (i, k(i))\}$ and shifted column $S = \{\langle 1, c_1 \rangle, \langle 2, c_2 \rangle, \dots, \langle \eta, c_\eta \rangle\}$, with $c_\eta < j$, $\eta \leq \sigma$, defines a facet of $\text{OP}_k(G)$ if and only if the following conditions hold:

- (1) there exists a node $v \in \{j, j + 1, \dots, \min(i - 1, k(i))\}$ with $v \notin \Gamma(i)$, and
- (2) U_c is not a clique for all $c \in \{c_1, c_1 + 1, \dots, j - 1\}$.

The proof appears in [33]. Note that \emptyset is not a clique. For orbitopes, SCIs do not define facets if $\eta \geq 2$ and $c_1 < c_2$, see [2]. We do not have to deal with this case explicitly, since then $G[U_{c_2}]$ is a clique of size one. In the case $j = k(i)$, SCIs are dominated by the set of inequalities that we describe in the next section.

4.3. Clique shifted column inequalities

Similarly to packing inequalities, SCIs may be combined with inequalities for the stable set problem to yield valid inequalities of $\text{OP}_k(G)$.

Proposition 21. Let $\alpha^T y \leq \beta$ be a non-trivial valid inequality for $P(G)$ with integral coefficients. Let $W := \{v \in V : \alpha_v \neq 0\}$ and $w = \max(W)$. Let S be a shifted column of $\text{col}(w - 1, j - 1)$ for some $1 < j \leq \min(W, k)$. Then

$$\sum_{v \in W} \alpha_v x_{vj} - x(S) \leq \beta - 1 \quad (31)$$

is a valid inequality for $\text{OP}_k(G)$.

Proof. Consider an integral point $\tilde{x} \in \text{OP}_k(G)$. Thus,

$$\tilde{\alpha} := \sum_{v \in W} \alpha_v \tilde{x}_{vj} \leq \beta$$

holds. If $\tilde{\alpha} \leq \beta - 1$, then Inequality (31) is obviously satisfied. Therefore, assume $\tilde{\alpha} = \beta$. Since $\alpha^T y \leq \beta$ is a non-trivial inequality, we have $\beta > 0$ and $\alpha \geq 0$, see Remark 2. Thus, there exists a $v \in W$ with $\tilde{x}_{vj} = 1$. Let $\langle \sigma, j \rangle = (v, j)$. Define

$$\tilde{S} = S \cap \{(\rho, t) : \rho \leq \sigma, t \in [j - 1]\}$$

to be the part of S that is below or on the diagonal $\text{diag}^{\leq} \langle \sigma, j - 1 \rangle$. Then \tilde{S} is a shifted column of $\text{col}(v - 1, j - 1)$. Hence, there exists an entry $(p, q) \in \tilde{S}$ with $x_{pq} = 1$, see [2, Lemma 8]. This shows that $\tilde{x}(S) \geq 1$, proving the validity of (31). \square

We again specialize to the case when $C = W$ (with $|C| \geq 2$) is a clique, i.e., $y(C) \leq 1$ is a clique inequality. Let $i = \max(C)$ and $1 < j \leq \min(C, k)$. Assume that S is a shifted column of $\text{col}(i - 1, j - 1)$. Then the corresponding *clique shifted column inequality* (CSCI) with leader (i, j) is

$$x(C \times \{j\}) - x(S) \leq 0,$$

which is valid by Proposition 21; the right-hand side of Fig. 12 contains an example. These inequalities were introduced in [2]. We define a CSCI to be *maximal* if the clique C is maximal in the subgraph $G[j, j + 1, \dots, i]$.

Remark 22. The conditions in Theorem 20 that guarantee SCIS to be facet-defining require $j < k(i)$. For $j = k(i)$, an SCI may be a CSCI if $\{j, j + 1, \dots, i\}$ is a stable set. In this case, the SCI/CSCI for $j = k(i)$ defines a facet as the following theorems show.

As for packing-clique inequalities, we differentiate between two cases for the characterization of the facet-defining properties. Proofs appear in [33].

Theorem 23. Let C be a clique, $i = \max(C)$, $1 < j \leq \min(C, k)$, and $j \in C$ such that $(i, j) = \langle \sigma, j \rangle$ with $\sigma > 1$. Then a CSCI with leader (i, j) defines a facet of $\text{OP}_k(G)$ if and only if

- (1) the CSCI is maximal, and
- (2) U_c is not a clique for all $c \in \{c_1, c_1 + 1, \dots, j - 1\}$.

For $(i, j) \in \mathcal{I}_{nk}$, a clique C in $G[j, \dots, i]$, and $j \notin C$, a maximal CSCI can only define a facet under certain conditions on the number of colors, similarly to the packing inequalities.

Theorem 24. Let C be a clique, let $i = \max(C)$, and let $1 < j \leq \min(C, k)$ be such that $j \notin C$ and $(i, j) = \langle \sigma, j \rangle$ with $\sigma > 1$. Then a CSCI with leader (i, j) defines a facet of $\text{OP}_k(G)$ if and only if the following conditions hold:

- (1) The CSCI is maximal.
- (2) U_c is not a clique for all $c \in \{c_1, c_1 + 1, \dots, c_\eta\}$.
- (3) The following must hold for $r = \min(C) - 1$ with $(r, j) = \langle \rho, j \rangle$:
 - For every $\langle \beta, c \rangle = (b, c)$ with $\beta = 1$, $b \in C$, and $j < c \leq k(b)$, there exists a node $v \in C \cap \{b + 1, b + 2, \dots, i\}$, such that $\{j, v\} \notin E$.
 - For every $\langle \beta, c \rangle = (b, c)$ with $b \in C$, $1 < \beta \leq \rho$, and $j < c \leq k(b)$, there exists a node $v \in \{j, j + 1, \dots, r\}$ with $\langle v, j \rangle = (v, j)$ such that $v < \beta$ that is not adjacent to at least one node in $C \setminus \{b\}$.

The third condition is the same as for packing-clique inequalities (Theorem 17) and depends on k : the example on the right-hand side of Fig. 12 shows a CSCI that defines a facet for $k = 3$, but not for $k = 4$.

5. Conclusion

The main topic of this paper is the polyhedral combination of the problem-specific structure for the maximum k -colorable subgraph problem with the symmetry handling structure of orbitopes. One motivation is our result that the weak LP-bound of the natural IP-formulation only slightly improves by adding orbitope symmetry handling. In our subsequent polyhedral investigation, we characterized a number of facet-defining inequalities. The structure of the graph influences most of these characterizations. The correspondence of nodes to rows (row labeling) is important, too. Therefore, the choice of the row labeling is important both for the theoretical and the practical properties of a given instance. In particular, we suspect that the labeling has a big influence on the performance of branch-and-cut algorithms.

A natural row labeling heuristic is to order nodes with respect to decreasing node degree, which might be beneficial because of the following two (heuristic) reasons. First, variable fixing by orbitope symmetry handling tends to happen toward the top of the matrix. If nodes with a high degree are affected, then this increases the chance of secondary fixings, e.g., due to edge inequalities. Second, such an ordering seems to produce stronger inequalities, such as the packing-clique inequalities. Here, the base node has to be adjacent to all nodes preceding it. The higher the degree of the base node, the higher are the chances of such an occurrence.

Future computational experiments will investigate the practical side of the results presented in this paper. In particular, we shall investigate different row labelings. Moreover, graph symmetries will be taken into account.

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